

**MAE 286 – Numerical Solution Techniques in Mechanical and Aerospace Engineering**

Fall 2009 – Main Campus

- References:** *Numerical Solution of Partial Differential Equations: Finite Difference Methods*, third edition, by G.D. Smith (Oxford University Press, 1985), ISBN 0198596502; *The Finite Element Method for Engineers*, fourth ed., by K.H. Huebner, D.L. Dewhurst, D.E. Smith, and T.G. Byrom (Wiley, 2001), ISBN 0471370789.
- Notes:** *Numerical Solution of Partial Differential Equations* by G.C. Everstine
- Instructor:** Gordon C. Everstine, <http://gwu.geverstine.com>  
gw(at)geverstine(dot)com, 301-977-0936
- Schedule:** Mondays, Aug. 31 – Dec. 14, 6:10 p.m. – 8:40 p.m.  
Mid-Term Exam: Oct. 26  
Final Exam: Dec. 14
- Description:** Development of finite difference and finite element techniques for solving elliptic, parabolic, and hyperbolic partial differential equations. Prerequisite: ApSc 213 or equivalent.
- Objectives:** To understand the fundamentals of finite difference and finite element solution of partial differential equations of engineering; to increase knowledge of the nature of solutions of equations of different types; to apply the numerical algorithms by solving various equations numerically.
- Grading:** Assignments 1/3, mid-term exam 1/3, final exam 1/3. All graded work must be completed in accordance with the GW Code of Academic Integrity (<http://www.gwu.edu/~ntegrity/code.html>). Students are encouraged to discuss the meaning of assignments and general approaches and strategies for handling those assignments, but it is not acceptable to share solutions and computer codes.

**Course Outline**

1. Ordinary differential equations; Euler's method; truncation error; Runge-Kutta methods; systems of equations; boundary value problems; finite differences; shooting methods
2. Classical equations of mathematical physics (Laplace, Poisson, wave, Helmholtz, heat); classification of PDEs; examples; transformation to non-dimensional form
3. Finite difference solution of parabolic equations; explicit and implicit methods; Crank-Nicolson method; stability
4. Finite difference solution of hyperbolic equations; domain of dependence; stability
5. Finite difference solution of elliptic equations; direct and iterative solution; derivative boundary conditions
6. Direct finite element analysis; spring, truss, and beam systems; matrix partitioning and constraints; 2-D continuum problems; change of basis
7. Calculus of variations; the brachistochrone; constraints
8. Variational principles; index notation and summation convention; deriving variational principles; shape functions; compatibility; element matrices; method of weighed residuals (Galerkin's method)
9. Potential fluid flow; symmetry; free surface flows; 2-D wave maker; variational principle; mechanical analogy